



Solvability of k-fractional Hilfer integral equations via Darbo's fixed point theorem

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ABSTRACT: In this article we are extended the Darbo's fixed point theorem using \mathcal{U} -class mapping. Using the Darbo type theorem, we give a solvability result for a k-fractional Hilfer integral equation along with an appropriate illustration.

Key Words: Measure of noncompactness, k-fractional Hilfer integral, fixed point theorem.

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1. Introduction

Kuratowski's measure of noncompactness (MNC), introduced in 1930 [20], has been extensively studied in various mathematical contexts. Different research papers have explored the application of this measure in different areas. Metwali et al. defined a novel MNC in variable exponent Lebesgue spaces, extending classical Lebesgue spaces and enabling the study of various equations [23]. Khokhar et al. proposed the concept of \mathcal{A} -condensing operators by utilizing the MNC, focusing on best proximity points and fractional differential equations [19]. Telli et al. utilized the Kuratowski MNC in studying boundary-value problems for fractional differential equations with variable order and delays, showcasing the applicability of the measure in stability criteria [31].

Caponetti et al. [4] analyzed the Kuratowski measure of noncompactness (MNC) in spaces of vector-valued functions, leading to new criteria for compactness based on quantitative features. The MNC is crucial in various fixed point theorems, which are instrumental in exploring solutions to different equations. For instance, the MNC helps in identifying solutions for nonlinear fractional integral equations within Banach spaces, as evidenced by Golshan [14], Deb et al. [11], Metwali [23], and Gabeleh et al. [13]. Their research demonstrates the use of MNC in Lebesgue spaces and sequence spaces to confirm the existence of solutions via fixed point theorems. Moreover, combining the MNC with other criteria, like the Hausdorff measure, enhances the effectiveness of fixed point theorems in analyzing the solvability of integral equations, highlighting the synergy between fixed point theorems and the MNC.

G. Darbo [7] extended Schauder's fixed point theorem by integrating Kuratowski's MNC into his framework. The MNC has proven vital in broadening Darbo's theorem across various mathematical contexts. Hammad et al. [15] introduced a new fixed point theorem that expands Darbo's theorem with the MNC, while Taoudi [30] generalized Darbo's principle using a monotone MNC with specific properties. Additionally, Salem et al. [28] applied the MNC within Banach spaces to address the existence of solutions for fractional Sturm–Liouville operators using fixed point theorems, including Darbo's. Collectively, these studies underscore the MNC's importance in extending Darbo's fixed point theorem and solving diverse mathematical problems.

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The Darbo fixed point theorem, a fundamental mathematical concept, has been extensively studied and generalized. It establishes the existence of fixed points for certain mappings in various spaces. Extensions and generalizations of Darbo's theorem include proofs of solution existence and stability for fractional integral equations [5,25], new generalizations with relaxed assumptions, and applications in Banach spaces with monotone MNC and convex mappings [26,30]. Additionally, new contraction types, such as the F-Darbo contraction, have been proposed, offering broader results and applications for solving integral equations [18].

J. Banaś [3] introduced the MNC in 1980, and its study in Banach spaces has since become a key research area. These measures play a crucial role in determining the existence of solutions to integral boundary value problems [22], studying the representation of an MNC and their applications in Banach spaces [6], exploring interpolation of an MNC of polynomials on Banach spaces [21], examining solvability conditions for fractional integral equations in Banach spaces using the theory of an MNC [8], and applying the MNC in characterizing classes of compact operators, solving integral equations, and establishing the existence of optimal solutions for systems of integro-differentials in Banach spaces [13]. These research efforts collectively contribute to a deeper understanding of MNCs and their diverse applications in various mathematical contexts.

Inspired and motivated by [9,10,16,24,27,29], in the context of an MNC. In this paper, we are generalized well-known theorems, namely, Darbo's fixed point theorem. the theorems was generalized with the help of \mathcal{U} -class mapping. Herein, first we presented a solvability result of a k -fractional Hilfer integral equation along with a suitable example using the Darbo type theorem.

Let $(E, \|\cdot\|)$ be a real Banach space and $B_r(\theta) = \{\zeta \in E : \|\zeta - \theta\| \leq r\}$. If $W(\neq \emptyset) \subseteq E$. Then

- \bar{W} = represents the closure of W ,
- $ConvW$ = represents the convex closure of W ,
- \mathfrak{B}_E = represents the set of all bounded and non-empty subsets of E
- \mathfrak{C}_E = represents the family of all relatively compact sets
- $\mathbb{R}_+ = [0, \infty)$.

The MNC is defined as [3].

Definition 1.1 A MNC is a function $\hat{\phi} : \mathfrak{B}_E \rightarrow [0, \infty)$ which fulfills the following axioms:

- (i) For all $W \in \mathfrak{B}_E$, we have $\hat{\phi}(W) = 0$ gives W is relatively compact.
- (ii) $\ker \hat{\phi} = \{W \in \mathfrak{B}_E : \hat{\phi}(W) = 0\} \neq \emptyset$ and $\ker \hat{\phi} \subset \mathfrak{C}_E$.
- (iii) $W \subseteq W_1 \implies \hat{\phi}(W) \leq \hat{\phi}(W_1)$.
- (iv) $\hat{\phi}(\bar{W}) = \hat{\phi}(W)$.
- (v) $\hat{\phi}(ConvW) = \hat{\phi}(W)$.
- (vi) $\hat{\phi}(\hat{\lambda}W + (1 - \hat{\lambda})W_1) \leq \hat{\lambda}\hat{\phi}(W) + (1 - \hat{\lambda})\hat{\phi}(W_1)$ for $\hat{\lambda} \in [0, 1]$.
- (vii) if $W_{\hat{k}} \in \mathfrak{B}_E$, $W_{\hat{k}} = \bar{W}_{\hat{k}}$, $W_{\hat{k}+1} \subset W_{\hat{k}}$, where $\hat{k} = 1, 2, 3, \dots$ and $\lim_{\hat{k} \rightarrow \infty} \hat{\phi}(W_{\hat{k}}) = 0$ then $\bigcap_{\hat{k}=1}^{\infty} W_{\hat{k}} \neq \emptyset$.

Here $\ker \hat{\phi}$ represents the *kernel of measure* $\hat{\phi}$. Since $\hat{\phi}(W_{\infty}) \leq \hat{\phi}(W_{\hat{k}})$ and $\hat{\phi}(W_{\infty}) = 0$. So, $W_{\infty} = \bigcap_{\hat{k}=1}^{\infty} W_{\hat{k}} \in \ker \hat{\phi}$.

Now we recall some definitions and theorems which are important in the context of present work:

Theorem 1.1 (Schauder [1]) Assume V is a non-empty, bounded, closed, and convex subset(NBCCS) of a Banach Space E . Then a continuous and compact function $\mathcal{A} : V \rightarrow V$ has at least one fixed point.

Theorem 1.2 (Darbo [7]) Assume V is a NBCCS of a Banach Space E . If a constant $\lambda \in [0, 1)$ exist for a continuous function $\mathcal{A} : V \rightarrow V$ such that

$$\hat{\phi}(\mathcal{A}W) \leq \lambda \hat{\phi}(W), \quad W \subseteq V.$$

Then \mathcal{A} must have a fixed point.

The following are some of the related concepts which will be require to construct an extended Darbo's fixed point theorem(DFPT).

Definition 1.2 A \mathcal{U} - class function is a continuous function $f : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}$, if it fulfills the following conditions:

- (1) $f(\hat{h}_1, \hat{h}_2) \leq \hat{h}_1 + \hat{h}_2$,
 - (2) $f(\hat{h}_1, \hat{h}_2) = \hat{h}_1$ implies that either $\hat{h}_1 = 0$ or $\hat{h}_2 = 0$.
- Also, $f(0, 0) = 0$.

For example,

- (1) $f(\hat{h}_1, \hat{h}_2) = \hat{h}_1 + \hat{h}_2$,
- (2) $f(\hat{h}_1, \hat{h}_2) = \rho \hat{h}_1$, $0 < \rho < 1$.

Definition 1.3 [17] Consider that Ψ is the collection of altering distance functions $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ fulfilling all the conditions:

- (1) $\psi(w_1) = 0 \iff w_1 = 0$.
- (2) ψ is a continuous and increasing.

Definition 1.4 [2] An ultra-altering distance function is a continuous functions $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ such that $\varphi(\varpi) > 0$, $\varphi(0) \geq 0$ and $\varpi > 0$.

2. Fixed point result

Theorem 2.1 Assume that \mathcal{W} is a NBCCS of a Banach space E . Moreover if, $\mathcal{A} : \mathcal{W} \rightarrow \mathcal{W}$ is continuous mapping with

$$\psi[\hat{\phi}(\mathcal{A}W)] \leq f[\psi(\hat{\phi}(W)), \varphi(\hat{\phi}(W))] - \varphi(\hat{\phi}(W)), \quad (2.1)$$

where $W \subset \mathcal{W}$, $\hat{\phi}$ is an arbitrary MNC, $f \in \mathcal{U}$, $\psi \in \Psi$ and φ is an ultra-altering distance function. Then \mathcal{W} contains at least one fixed point of \mathcal{A} .

Proof: In order to obtain the main result, we first build a nested sequence and then we will apply the concept of the MNC. Construct a sequence $\{\mathcal{W}_n\}_{n=1}^{\infty}$ with $\mathcal{W}_1 = \mathcal{W}$ and $\mathcal{W}_{n+1} = \text{Conv}(\mathcal{A}\mathcal{W}_n)$ for $n \in \mathbb{N}$. Also $\mathcal{A}\mathcal{W}_1 = \mathcal{A}\mathcal{W} \subseteq \mathcal{W} = \mathcal{W}_1$, $\mathcal{W}_2 = \text{Conv}(\mathcal{A}\mathcal{W}_1) \subseteq \mathcal{W} = \mathcal{W}_1$. Proceeding in the same way we get $\mathcal{W}_1 \supseteq \mathcal{W}_2 \supseteq \mathcal{W}_3 \supseteq \dots \supseteq \mathcal{W}_n \supseteq \mathcal{W}_{n+1} \supseteq \dots$.

If $n_0 \in \mathbb{N}$ exists which fulfill the condition $f[\psi(\hat{\phi}(\mathcal{W}_{n_0})), \varphi(\hat{\phi}(\mathcal{W}_{n_0}))] = 0$. Then $\hat{\phi}(\mathcal{W}_{n_0}) = 0$, so \mathcal{W}_{n_0} is a compact set. Then by virtue of Schauder's theorem, \mathcal{A} must have a fixed point in \mathcal{W} .

Consider $f[\psi(\hat{\phi}(\mathcal{W}_n)), \varphi(\hat{\phi}(\mathcal{W}_n))] > 0$, $n \in \mathbb{N}$.

Then for $n \in \mathbb{N}$ we have,

$$\begin{aligned} & \psi(\hat{\phi}(\mathcal{W}_{n+1})) \\ &= \psi[\hat{\phi}(\text{Conv}\mathcal{A}\mathcal{W}_n)] \\ &= \psi[\hat{\phi}(\mathcal{A}\mathcal{W}_n)] \\ &\leq f[\psi(\hat{\phi}(\mathcal{W}_n)), \varphi(\hat{\phi}(\mathcal{W}_n))] - \varphi(\hat{\phi}(\mathcal{W}_n)) \\ &\leq \psi(\hat{\phi}(\mathcal{W}_n)). \end{aligned}$$

As the mapping ψ is a non-decreasing, we get

$$\hat{\phi}(\mathcal{W}_{n+1}) \leq \hat{\phi}(\mathcal{W}_n).$$

Then, $\{\hat{\phi}(\mathcal{W}_n)\}$ is a decreasing and bounded below sequence.

Its follows converges to $k = \inf \{\mathcal{W}_n\}$.

If possible let $k > 0$. By using (2.3), we get

$$\begin{aligned}\psi(\hat{\phi}(\mathcal{W}_{n+1})) &= \psi[\hat{\phi}(\text{Conv}\mathcal{A}\mathcal{W}_n)] \\ &\leq f[\psi(\hat{\phi}(\mathcal{W}_n)), \varphi(\hat{\phi}(\mathcal{W}_n))] - \varphi(\hat{\phi}(\mathcal{W}_n)).\end{aligned}$$

As $n \rightarrow \infty$, we obtain

$$\psi(k) \leq f[\psi(k), \varphi(k)] - \varphi(k) \leq \psi(k).$$

Its follows that

$$f[\psi(k), \varphi(k)] = \psi(k).$$

Using by (2) of Definition 1.2, we get

$$\psi(k) = 0 \text{ or } \varphi(k) = 0.$$

Using by (1) of Definition 1.3, we obtain,

$$\begin{aligned}k &= 0 \\ \implies \lim_{n \rightarrow \infty} \hat{\phi}(\mathcal{W}_n) &= 0.\end{aligned}$$

Since $\mathcal{W}_n \supseteq \mathcal{W}_{n+1}$, by virtue of Definition 1.1, $\mathcal{W}_\infty = \bigcap_{n=1}^\infty \mathcal{W}_n$ must be non-empty, closed and convex subset of \mathcal{W} and under \mathcal{A} , \mathcal{W}_∞ is invariant. Therefore if we apply Theorem 1.1 we can conclude that \mathcal{A} must have a fixed point in \mathcal{W} . Which concludes the proof. \square

Theorem 2.2 Assume that \mathcal{W} is a NBCCS of a Banach space E . Also a continuous mapping $\mathcal{A} : \mathcal{W} \rightarrow \mathcal{W}$ satisfies the condition

$$\psi[\hat{\phi}(\mathcal{A}W)] \leq \psi(\hat{\phi}(W))\beta[\psi(\hat{\phi}(W))] - \varphi(\hat{\phi}(W)), \quad (2.2)$$

where $\hat{\phi}$ is an arbitrary MNC, $W \subset \mathcal{W}$, $\psi \in \Psi$ and φ is an ultra-altering distance function. Also, let $\beta : \mathbb{R}_+ \rightarrow [0, 1)$ be a continuous function. Then, \mathcal{A} has at least one fixed point in \mathcal{W} .

Proof: Theorem 2.2 can be proved by putting $f(w_1, w_2) = w_1\beta(w_1)$ in Theorem 2.1. \square

Theorem 2.3 Assume that \mathcal{W} is a NBCCS of a Banach space E . Also let $\beta : \mathbb{R}_+ \rightarrow [0, 1)$ be a continuous function and if a continuous mapping $\mathcal{A} : \mathcal{W} \rightarrow \mathcal{W}$ satisfies the condition

$$\hat{\phi}(\mathcal{A}W) \leq \hat{\phi}(W)\beta[\hat{\phi}(W)] - \varphi(\hat{\phi}(W)), \quad (2.3)$$

where $W \subset \mathcal{W}$, $\hat{\phi}$ is an arbitrary MNC and φ is an ultra-altering distance function. Then in \mathcal{W} , \mathcal{A} has at least one fixed point.

Proof: Theorem 2.3 can be obtain by putting $\psi(w_1) = w_1$ in Theorem 2.2. \square

Corollary 2.1 Assume that \mathcal{W} is a NBCCS of a Banach space E . Also $\beta : \mathbb{R}_+ \rightarrow [0, 1)$ be a continuous mapping and let a continuous mapping $\mathcal{A} : \mathcal{W} \rightarrow \mathcal{W}$ fulfills the conditions

$$\hat{\phi}(\mathcal{A}W) \leq [\beta\{\hat{\phi}(W)\} - 1]\hat{\phi}(W), \quad (2.4)$$

where $\hat{\phi}$ is an arbitrary MNC and $W \subset \mathcal{W}$. Then, \mathcal{W} contains at least one fixed point of \mathcal{A} .

Proof: Corollary 2.1 can be proved by putting $\varphi(w_1) = w_1$ in Theorem 2.3. \square

Corollary 2.2 Assume that \mathcal{W} is a NBCCS of a Banach space E . Also let a continuous mapping $\mathcal{A} : \mathcal{W} \rightarrow \mathcal{W}$ satisfies the condition

$$\hat{\phi}(\mathcal{A}W) \leq h\hat{\phi}(W), \quad (2.5)$$

where $W \subset \mathcal{W}$, $\hat{\phi}$ is an arbitrary MNC. Then, \mathcal{A} has at least one fixed point in \mathcal{W} .

Proof: In Theorem 2.3 by substituting $\beta(w_1) = \frac{1}{k}$ and $h = \frac{1-k}{k}$, we obtain the Darbo's theorem. \square

3. Measure of noncompactness on $C(I)$

Let us consider the real continuous function space $E = C(I)$ on I , where $I = [0, T]$ equipped with the norm

$$\|\Delta\| = \sup \{|\Delta(w_1)| : w_1 \in I\}, \Delta \in E.$$

Consider a bounded subset $W (\neq \emptyset)$ of E . The modulus of the continuity of Δ denoted by $\hat{\varphi}(\Delta, \varepsilon)$ for $\Delta \in W$ and $\varepsilon > 0$ is define as

$$\hat{\varphi}(\Delta, \varepsilon) = \sup \{|\Delta(w_1) - \Delta(w_2)| : w_1, w_2 \in I, |w_1 - w_2| \leq \varepsilon\}.$$

Further, let us set

$$\hat{\varphi}(W, \varepsilon) = \sup \{\hat{\varphi}(\Delta, \varepsilon) : \Delta \in W\}; \quad \hat{\varphi}_0(W) = \lim_{\varepsilon \rightarrow 0} \hat{\varphi}(W, \varepsilon).$$

Then the function $\hat{\varphi}_0$ is generally known to be a MNC in E , with $\Theta(W) = \frac{1}{2}\hat{\varphi}_0(W)$ (see [3]) as the Hausdorff MNC Θ .

4. Solvability of k-fractional integral equations

In this present section of the paper, we will demonstrate how we can apply our conclusions in regard to the existence result of a fractional integral equation in Banach space.

Assume $k \in \mathbb{N}$, $\alpha \in \mathbb{C} : \mathbb{R}(\alpha) \in (n-1, n]$, $n \in \mathbb{N}$, where $\mathbb{R}(\cdot)$ represents the real part of a complex number, the k-fractional Hilfer integral is defined by [12]

$$I_k^\alpha[f(\varrho)] = \frac{1}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} f(\hat{\xi}) d\hat{\xi}; \quad \varrho \in [0, T].$$

In this study, we will be considering a functional integral equation:

$$L = \Delta(\varrho, H(\varrho, L(\varrho)), (I_k^\alpha L)(\varrho)), \quad (4.1)$$

where $0 < \alpha, k < 1$, and $\vartheta \in I = [0, T]$.

Let define

$$B_{r_0} = \{L \in X : \|L\| \leq r_0\}.$$

Assume that

- (A) $H : I \times \mathbb{R} \rightarrow \mathbb{R}$, $\Delta : I \times \mathbb{R}^2 \rightarrow \mathbb{R}$ be continuous functions and constants $c_i \geq 0$; $i = 1, 2, 3$ exists satisfying the conditions

$$|\Delta(\varrho, H, I_1) - \Delta(\varrho, \bar{H}, \bar{I}_1)| \leq c_1 |H - \bar{H}| + c_2 |I_1 - \bar{I}_1|, \quad \varrho \in I, I_1, \bar{I}_1 \in \mathbb{R}$$

and

$$|H(\varrho, L_1) - H(\varrho, \bar{L}_1)| \leq c_3 |L_1 - \bar{L}_1|, \quad \varrho \in I, L_1, \bar{L}_1 \in \mathbb{R}.$$

- (B) A constant $r_0 > 0$ exists which satisfies the conditions

$$\bar{\Delta} = \sup \{|\Delta(\varrho, H, I_1)| : \varrho \in I, H \in [-\bar{H}, \bar{H}], I_1 \in [-\bar{I}, \bar{I}]\} \leq r_0,$$

and $c_1 c_3 < 1$. Here,

$$\bar{H} = \sup \{|H(\varrho, L(\varrho))| : \varrho \in I, L(\varrho) \in [-r_0, r_0]\}$$

and

$$\bar{I} = \sup \{|(I_k^\alpha L)(\varrho)| : \varrho \in I, L(\varrho) \in [-r_0, r_0]\}.$$

- (C) $\max |\Delta(\varrho, 0, 0)| = M$ and $H(\varrho, 0) = 0$ for all $\varrho \in I$.

- (D) A positive solution r_0 exists such that

$$c_1 c_3 r_0 + M + \frac{c_2 r_0}{\alpha \Gamma_k(\alpha)} T^{\alpha/k} \leq r_0.$$

Theorem 4.1 *If the assumptions (A)-(D) holds, then the equation (4.1) has at least one solution in $E = C(I)$.*

Proof: Let $\mathcal{D} : E \rightarrow E$ be an operator defined by:

$$(\mathcal{D}L)(\varrho) = \Delta(\varrho, H(\varrho, L(\varrho)), (I_k^\alpha L)(\varrho)).$$

1st Step: We show that \mathcal{D} maps B_{r_0} into B_{r_0} . Let $L \in B_{r_0}$, We have

$$\begin{aligned} & |(\mathcal{D}L)(\varrho)| \\ & \leq |\Delta(\varrho, H(\varrho, L(\varrho)), (I_k^\alpha L)(\varrho)) - \Delta(\varrho, 0, 0)| + |\Delta(\varrho, 0, 0)| \\ & \leq c_1 |H(\varrho, L(\varrho))| + c_2 |(I_k^\alpha L)(\varrho)| + |\Delta(\varrho, 0, 0)| \\ & \leq c_1 c_3 |L(\varrho)| + c_2 |(I_k^\alpha L)(\varrho)| + M. \end{aligned}$$

Also,

$$\begin{aligned} |(I_k^\alpha L)(\varrho)| &= \left| \frac{1}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} \right| \\ &\leq \frac{1}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} |L(\hat{\xi})| d\hat{\xi} \\ &\leq \frac{r_0}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} d\hat{\xi} \\ &\leq \frac{r_0}{\alpha\Gamma_k(\alpha)} T^{\alpha/k}. \end{aligned}$$

Hence, $\|L\| < r_0$ gives

$$\|\mathcal{D}L\| \leq c_1 c_3 r_0 + M + \frac{c_2 r_0}{\alpha\Gamma_k(\alpha)} T^{\alpha/k} \leq r_0.$$

It follows from the assumption (D) that \mathcal{D} maps B_{r_0} into B_{r_0} .

2nd Step: Next, we claim that \mathcal{D} is continuous on B_{r_0} . Fix $\delta > 0$ and let $L, \bar{L} \in B_{r_0}$ such that $\|L - \bar{L}\| < \delta$. For all $x \in I$, we now obtain

$$\begin{aligned} & |(\mathcal{D}L)(\varrho) - (\mathcal{D}\bar{L})(\varrho)| \\ &= |\Delta(\varrho, H(\varrho, L(\varrho)), (I_k^\alpha L)(\varrho)) - \Delta(\varrho, H(\varrho, \bar{L}(\varrho)), (I_k^\alpha \bar{L})(\varrho))| \\ &\leq c_1 |H(\varrho, L(\varrho)) - H(\varrho, \bar{L}(\varrho))| + c_2 |(I_k^\alpha L)(\varrho) - (I_k^\alpha \bar{L})(\varrho)| \\ &\leq c_1 c_3 \|L - \bar{L}\| + c_2 |(I_k^\alpha L)(\varrho) - (I_k^\alpha \bar{L})(\varrho)| \\ &\leq c_1 c_3 \|L - \bar{L}\| + c_2 |(I_k^\alpha L)(\varrho) - (I_k^\alpha \bar{L})(\varrho)|. \end{aligned}$$

Moreover,

$$\begin{aligned} & |(I_k^\alpha L)(\varrho) - (I_k^\alpha \bar{L})(\varrho)| \\ &= \left| \frac{1}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} (L(\hat{\xi}) - \bar{L}(\hat{\xi})) d\hat{\xi} \right| \\ &\leq \frac{1}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} |L(\hat{\xi}) - \bar{L}(\hat{\xi})| d\hat{\xi} \\ &< \frac{\delta}{k\Gamma_k(\alpha)} \int_0^\varrho (\varrho - \hat{\xi})^{\frac{\alpha}{k}-1} d\hat{\xi} \\ &< \frac{\delta}{\alpha\Gamma_k(\alpha)} T^{\alpha/k}. \end{aligned}$$

Hence, $\|L - \bar{L}\| < \delta$ gives

$$|(\mathcal{D}L)(\varrho) - (\mathcal{D}\bar{L})(\varrho)| < c_1 c_3 \delta + c_2 \frac{\delta}{\alpha\Gamma_k(\alpha)} T^{\alpha/k}.$$

As $\delta \rightarrow 0$, we get

$$|(\mathcal{D}L)(\vartheta) - (\mathcal{D}\bar{L})(\varrho)| \rightarrow 0,$$

which indicates that \mathcal{D} is continuous on B_{r_0} .

3rd Step: Here, we estimate \mathcal{D} is relation to $\hat{\varphi}_0$. Consider that $\varpi(\neq \emptyset) \subseteq B_{r_0}$. Let $\delta > 0$ be arbitrary and choose $L \in \varpi$ with $\varrho_1, \varrho_2 \in I$ such that $|\varrho_2 - \varrho_1| \leq \delta$ and $\varrho_2 \geq \varrho_1$.

Now,

$$\begin{aligned} & |(\mathcal{D}L)(\varrho_2) - (\mathcal{D}L)(\varrho_1)| \\ &= |\Delta(\varrho_2, H(\varrho_2, L(\varrho_2)), (I_k^\alpha L)(\varrho_2)) - \Delta(\varrho_1, H(\varrho_1, L(\varrho_1)), (I_k^\alpha L)(\varrho_1))| \\ &\leq |\Delta(\varrho_2, H(\varrho_2, L(\varrho_2)), (I_k^\alpha L)(\varrho_2)) - \Delta(\varrho_2, H(\varrho_2, L(\varrho_2)), (I_k^\alpha L)(\varrho_1))| \\ &\quad + |\Delta(\varrho_2, H(\varrho_2, L(\varrho_2)), (I_k^\alpha L)(\varrho_1)) - \Delta(\varrho_2, H(\varrho_1, L(\varrho_1)), (I_k^\alpha L)(\varrho_1))| \\ &\quad + |\Delta(\varrho_2, H(\varrho_1, L(\varrho_1)), (I_k^\alpha L)(\varrho_1)) - \Delta(\varrho_1, H(\varrho_1, L(\varrho_1)), (I_k^\alpha L)(\varrho_1))| \\ &\leq c_2 |(I_k^\alpha L)(\varrho_2) - (I_k^\alpha L)(\varrho_1)| + c_1 |H(\varrho_2, L(\varrho_2)) - H(\varrho_1, L(\varrho_1))| + \beta_\Delta(I, \delta) \\ &\leq c_2 |(I_k^\alpha L)(\varrho_2) - (I_k^\alpha L)(\varrho_1)| + c_1 c_3 |L(\varrho_2) - L(\varrho_1)| + \beta_\Delta(I, \delta), \end{aligned}$$

where

$$\beta_\Delta(I, \delta) = \sup \left\{ |\Delta(\varrho_2, H, I_1) - \Delta(\varrho_1, H, I_1)| : |\varrho_2 - \varrho_1| \leq \delta; \varrho_1, \varrho_2 \in I; \right. \\ \left. H \in [-\bar{H}, \bar{H}], I_1 \in [-\bar{I}, \bar{I}] \right\}.$$

Also,

$$\begin{aligned} & |(I_k^\alpha L)(\varrho_2) - (I_k^\alpha L)(\varrho_1)| \\ &= \left| \frac{1}{k\Gamma_k(\alpha)} \int_0^{\varrho_2} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} - \frac{1}{k\Gamma_k(\alpha)} \int_0^{\varrho_1} (\varrho_1 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} \right| \\ &\leq \frac{1}{k\Gamma_k(\alpha)} \left| \int_0^{\varrho_2} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} - \int_0^{\varrho_1} (\varrho_1 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} \right| \\ &\leq \frac{1}{k\Gamma_k(\alpha)} \left| \int_0^{\varrho_2} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} - \int_0^{\varrho_1} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} \right| \\ &\quad + \frac{1}{k\Gamma_k(\alpha)} \left| \int_0^{\vartheta_1} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} - \int_0^{\varrho_1} (\varrho_1 - \hat{\xi})^{\frac{\alpha}{k}-1} L(\hat{\xi}) d\hat{\xi} \right| \\ &\leq \frac{\|L\|}{k\Gamma_k(\alpha)} \left| \int_{\varrho_1}^{\vartheta_2} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} d\hat{\xi} + \int_0^{\varrho_1} (\varrho_2 - \hat{\xi})^{\frac{\alpha}{k}-1} d\hat{\xi} - \int_0^{\varrho_1} (\varrho_1 - \hat{\xi})^{\frac{\alpha}{k}-1} d\hat{\xi} \right| \\ &\leq \frac{\|L\|}{k\Gamma_k(\alpha)} \left| (\varrho_2 - \varrho_1)^{\frac{\alpha}{k}} + \varrho_2^{\frac{\alpha}{k}} - (\varrho_2 - \varrho_1)^{\frac{\alpha}{k}} - \varrho_1^{\frac{\alpha}{k}} \right|. \end{aligned}$$

As $\delta \rightarrow 0$, then $\varrho_2 \rightarrow \varrho_1$ and so,

$$|(I_k^\alpha L)(\varrho_2) - (I_k^\alpha L)(\varrho_1)| \rightarrow 0.$$

Hence,

$$|(\mathcal{D}L)(\varrho_2) - (\mathcal{D}L)(\varrho_1)| \leq c_2 |(I_k^\alpha L)(\varrho_2) - (I_k^\alpha L)(\varrho_1)| + c_1 c_3 |L(\varrho_2) - L(\varrho_1)| + \beta_\Delta(I, \delta).$$

Which yields,

$$\hat{\varphi}(\mathcal{D}L, \delta) \leq c_1 c_3 |L(\varrho_2) - L(\varrho_1)| + \beta_\Delta(I, \delta).$$

It is derived from the uniform continuity of Δ on $I \times [-\bar{H}, \bar{H}] \times [-\bar{I}, \bar{I}]$ that $\lim_{\delta \rightarrow 0} \beta_\Delta(I, \delta) \rightarrow 0$, as $\delta \rightarrow 0$.

Setting $\sup_{L \in \varpi}$ as well as $\delta \rightarrow 0$, we obtain

$$\hat{\varphi}_0(\mathcal{D}\varpi) \leq c_1 c_3 \hat{\varphi}_0(\varpi).$$

By Corollary 2.2, we can state that \mathcal{D} possess a fixed point in $\Delta \subseteq B_{r_0}$. This means that in the space E the Equation (4.1) has a solution. \square

Example 4.1 Consider the following fractional integral equation:

$$L(\varrho) = \frac{L(\varrho)}{15 + \varrho^2} + \frac{I_{\frac{2}{5}} L(\varrho)}{25} + g(\varrho) \quad (4.2)$$

for $\varrho \in [0, 2] = I$.

Here,

$$g(\varrho) = k^2 e^{-\frac{\alpha}{k}\varrho} \frac{9 + e^{\frac{\alpha}{k}\varrho}}{10 + e^{\frac{\alpha}{k}\varrho}} = \frac{1}{25} e^{-2\varrho} \frac{9 + e^{2\varrho}}{10 + e^{2\varrho}}$$

and

$$I_{\frac{2}{5}} L(\varrho) = \frac{5}{\Gamma_{1/5}(2/5)} \int_0^\varrho (\varrho - \xi) L(\xi) d\xi.$$

Also,

$$\Delta(\varrho, H, I_1) = \frac{1}{25} e^{-2\varrho} \frac{9 + e^{2\varrho}}{10 + e^{2\varrho}} + H + \frac{I_1}{25}$$

and

$$H(\varrho, L) = \frac{L}{15 + \varrho^2}.$$

Obviously, both Δ and H are continuous and satisfies the conditions:

$$|H(\varrho, L_1) - H(\varrho, L_2)| \leq \frac{|L_1 - L_2|}{15}$$

and

$$|\Delta(\varrho, H, I_1) - \Delta(\varrho, \bar{H}, \bar{I}_1)| \leq |H - \bar{H}| + \frac{1}{25} |I_1 - \bar{I}_1|,$$

respectively. Therefore

$$c_1 = 1, \quad c_2 = \frac{1}{25}, \quad c_3 = \frac{1}{15} \quad \text{and} \quad c_1 c_3 = \frac{1}{15} < 1.$$

If $\|L\| \leq r_0$, then

$$\bar{H} = \frac{r_0}{15}$$

and

$$\bar{I}_1 = \frac{10r_0}{\Gamma_{1/5}(2/5)}.$$

Further,

$$|\Delta(\varrho, H, I_1)| \leq \frac{r_0}{15} + \frac{1}{25} \cdot \frac{10r_0}{\Gamma_{1/5}(2/5)} + \frac{2}{55} \leq r_0.$$

If we choose $r_0 = 2$, then

$$\bar{H} = \frac{2}{15}$$

and

$$\bar{I}_1 = \frac{20}{\Gamma_{1/5}(2/5)}.$$

which gives

$$\bar{\Delta} = 0.667355 \leq 2.$$

However, also for $r_0 = 2$, assumption (D) is satisfied.

Consequently, we have achieved all of the assumptions of Theorem 4.1 from (A) to (D). Therefore from Theorem 4.1, we can say that the equation (4.2) has a solution in $E = C(I)$.

Example 4.2 Consider the following fractional integral equation:

$$L(\varrho) = \frac{L(\varrho)}{5 + \varrho^4} + \frac{I_{\frac{2}{3}}^{\frac{2}{3}} L(\varrho)}{8} + g(\varrho) \quad (4.3)$$

for $\varrho \in [0, 3] = I$.

Here,

$$g(\varrho) = k^2 e^{-\frac{\alpha}{k}\varrho} \frac{3 + \varrho^{\frac{\alpha}{k}}}{15 + \varrho^{\frac{\alpha}{k}}} = \frac{1}{9} e^{-2\varrho} \frac{3 + \varrho^2}{15 + \varrho^2}$$

and

$$I_{\frac{2}{3}}^{\frac{2}{3}} L(\varrho) = \frac{3}{\Gamma_{1/3}(2/3)} \int_0^\varrho (\varrho - \xi) L(\xi) d\xi.$$

Also,

$$\Delta(\varrho, H, I_1) = \frac{1}{9} e^{-2\varrho} \frac{3 + \varrho^2}{15 + \varrho^2} + H + \frac{I_1}{8}$$

and

$$H(\varrho, L) = \frac{L}{5 + \varrho^4}.$$

Obviously, both Δ and H are continuous and satisfies the conditions:

$$|H(\varrho, L_1) - H(\varrho, L_2)| \leq \frac{|L_1 - L_2|}{5}$$

and

$$|\Delta(\varrho, H, I_1) - \Delta(\varrho, \bar{H}, \bar{I}_1)| \leq |H - \bar{H}| + \frac{1}{8} |I_1 - \bar{I}_1|,$$

respectively. Therefore

$$c_1 = 1, \quad c_2 = \frac{1}{8}, \quad c_3 = \frac{1}{5} \quad \text{and} \quad c_1 c_3 = \frac{1}{5} < 1.$$

If $\|L\| \leq r_0$, then

$$\bar{H} = \frac{r_0}{5}$$

and

$$\bar{I}_1 = \frac{27r_0}{2\Gamma_{1/3}(2/3)}.$$

Further,

$$|\Delta(\varrho, H, I_1)| \leq \frac{r_0}{5} + \frac{1}{8} \cdot \frac{27r_0}{2\Gamma_{1/3}(2/3)} + \frac{1}{45} \leq r_0.$$

If we choose $r_0 = 3$, then

$$\bar{H} = \frac{2}{5}$$

and

$$\bar{I}_1 = \frac{81}{2\Gamma_{1/3}(2/3)}.$$

which gives

$$\bar{\Delta} = 2.52745 \leq 3.$$

However, also for $r_0 = 3$, assumption (D) is satisfied.

Consequently, we have achieved all of the assumptions of Theorem 4.1 from (A) to (D). Therefore from Theorem 4.1, we can say that the equation (4.3) has a solution in $E = C(I)$.

5. Conclusion

Using generalized Darbo's fixed point theorem along with \mathcal{U} -class mappings, we can derive new results concerning fixed point theorems. This approach presents that Darbo's fixed point theorem is effective in establishing important fixed point results, particularly in proving the existence of solutions for a specific type of k -fractional Hilfer integral equation.

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