



On Integral Relations of Incomplete Aleph-functions and Applications

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ABSTRACT: Aleph (\aleph)-functions are very general and advanced types of mathematical functions used in many areas. Over time, they have been extended in different ways, one of which is the incomplete Aleph-function. In this paper, we find integral relations for incomplete Aleph-functions and use them to solve double integrals that involve Bessel functions, hypergeometric functions, and incomplete Aleph-functions. We show that these double integrals can be solved more easily when certain known results are used. The results we present are quite general, and we also give some specific examples to show how they work in special cases.

Keywords: Incomplete Gamma functions, Bessel functions, Gauss hypergeometric functions, Mellin-Barnes contour integrals, Aleph-functions, incomplete Aleph-functions, integral relations.

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1. Introduction

The Aleph-function (written as \aleph) (see [1], [2]) is a type of special function in mathematics. It is broader than some other well-known functions, such as the I -function (see [3]) and the H -function (see [4]), because these functions can be obtained as particular cases of it. The Aleph-function is very useful and has been applied in many areas. For instance, one of its special cases has been used in the study of fractional driftless Fokker–Planck equations with power-law diffusion coefficients. It also has important applications in several other fields. For example, Saxena and Pogány [5] gave closed-form results for a family of Mathieu-type \mathbf{a} -series that contain the Aleph-function in their terms. Chaurasia and Singh [6] formulated a representation of Lambert’s law involving the Aleph-function. Prakash and Agnihotri [7] explored double integral transform of Aleph-function which leads to the formation of another important process of augmenting in Aleph-function. Chaurasia and Gill [8] obtained two integral formulas involving the Aleph-function, which generate a broad class of elliptic-type integrals. Dubey [9] represented a blood glucose equation with the help of the Aleph-function. Ayant and Kumar [10] solved a multiple integral involving the Aleph-function, which led to the derivation of a multiple exponential Fourier series. Using operational methods, Agarwal et al. [11] constructed a sequence of functions based on the Aleph-function (see also [12,13]). Moreover, the Aleph-function has significant uses in fractional calculus, which studies integrals and derivatives of non-integer order (see [14,15,16],).

The incomplete Aleph-function is a special mathematical function that generalizes the usual Aleph-function (\aleph -function). This function is important and has been applied in many areas of mathematics and science. For instance, Dinesh et al. [17] investigated certain unified infinite integrals involving incomplete Aleph-functions, (see also [18]). Sachan et al. [19] proposed solutions to the axisymmetric Dirichlet potential problem for a half-space using incomplete Aleph-functions. Tyagi et al. [20] used

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Jacobi polynomials, multivariable Aleph-functions, incomplete Fox's Wright functions, and incomplete Aleph-functions to analyze the deflection and bending stresses of a clamped circular plate under uneven loading. Sachan and Ayant [21] evaluated finite integrals that included elliptic integrals of the first kind, extended Mittag-Leffler functions, and incomplete Aleph-functions. Kumar and Dassani [22] solved Fredholm integral equations with kernels that involved the S -function, extended Mittag-Leffler function, and incomplete \aleph -function. Sachan et al. [23] worked on finite integrals combining Fresnel integrals with incomplete Aleph-functions. Singh et al. [24] expressed Beer-Lambert's law using incomplete Aleph-functions. Singh et al. [25] also solved modified fractional kinetic equations with incomplete Aleph-functions through Elzaki and inverse Elzaki transforms. Moreover, Kumar et al. [26] studied finite integrals related to incomplete Aleph-functions.

The *incomplete Aleph-functions* $(\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ and $(\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ are defined as follows, (see, [27]);

$$\begin{aligned} (\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z) &= (\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n} \left[z \left| \begin{array}{l} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, n}, [\tau_i (a_{ji}, \mathcal{B}_{ji})]_{n+1, p_i} \\ (g_j, \mathcal{G}_j)_{1, m}, [\tau_i (g_{ji}, \mathcal{G}_{ji})]_{m+1, q_i} \end{array} \right. \right] \\ &= \frac{1}{2\pi\omega} \int_L \phi_1(s, \xi) z^{-s} ds, \end{aligned} \quad (1.1)$$

where, $\omega = \sqrt{-1}$,

$$\phi_1(s, \xi) = \frac{\Gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\sum_{i=1}^r \tau_i \left[\prod_{j=m+1}^{q_i} \Gamma(1 - g_{ji} - \mathcal{G}_{ji} s) \prod_{j=n+1}^{p_i} \Gamma(a_{ji} + \mathcal{B}_{ji} s) \right]} \quad (1.2)$$

and

$$\begin{aligned} (\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z) &= (\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n} \left[z \left| \begin{array}{l} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, n}, [\tau_i (a_{ji}, \mathcal{B}_{ji})]_{n+1, p_i} \\ (g_j, \mathcal{G}_j)_{1, m}, [\tau_i (g_{ji}, \mathcal{G}_{ji})]_{m+1, q_i} \end{array} \right. \right] \\ &= \frac{1}{2\pi\omega} \int_L \phi_2(s, \xi) z^{-s} ds, \end{aligned} \quad (1.3)$$

where

$$\phi_2(s, \xi) = \frac{\gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\sum_{i=1}^r \tau_i \left[\prod_{j=m+1}^{q_i} \Gamma(1 - g_{ji} - \mathcal{G}_{ji} s) \prod_{j=n+1}^{p_i} \Gamma(a_{ji} + \mathcal{B}_{ji} s) \right]}. \quad (1.4)$$

Here $\gamma(\vartheta, \xi)$ and $\Gamma(\vartheta, \xi)$ are the incomplete gamma functions defined as follows:

$$\gamma(\vartheta, \xi) = \int_0^\xi u^{\vartheta-1} e^{-u} du \quad (\xi \geq 0; \Re(\vartheta) > 0) \quad (1.5)$$

and

$$\Gamma(\vartheta, \xi) = \int_\xi^\infty u^{\vartheta-1} e^{-u} du \quad (\xi \geq 0; \Re(\vartheta) > 0 \text{ when } \xi = 0). \quad (1.6)$$

The sum of the functions given in (1.5) and (1.6) results in the familiar Gamma function (see, e.g., [28, Section 1.1]):

$$\Gamma(\vartheta) = \gamma(\vartheta, \xi) + \Gamma(\vartheta, \xi) = \int_0^\infty u^{\vartheta-1} e^{-u} du \quad (\Re(\vartheta) > 0). \quad (1.7)$$

The incomplete \aleph -functions $(\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ and $(\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ in (1.1) and (1.3) exist for $\xi \geq 0$ under following conditions: The contour L is of Mellin-Barnes type and runs from $\varrho - i\infty$ to $\varrho + i\infty$ for some real ϱ with indentations, if necessary, so that the poles of $\Gamma(1 - a_j - \mathcal{B}_j s)$, $j = 2, \dots, n$, can be placed to the right of the contour L and the poles of $\Gamma(g_j + \mathcal{G}_j s)$, $j = 1, \dots, m$, to the left of the contour L . The quantities τ_i, m, n, p_i, q_i are non-negative integers satisfying $0 \leq n \leq p_i, 0 \leq m \leq q_i$; a_j, g_j, a_{ji}, g_{ji} are complex number parameters and $\mathcal{B}_j, \mathcal{G}_j, \mathcal{B}_{ji}, \mathcal{G}_{ji}$ are positive real number parameters. Assume that all poles of (1.2) and (1.4) are simple and the empty product there (elsewhere) is (as usual) interpreted to be unity. The following conditions hold :

$$\Omega_i > 0, \quad |\arg(z)| < \frac{\pi}{2}\Omega_i, \quad i = 1, \dots, r \quad (1.8)$$

$$\Omega_i \geq 0, \quad |\arg(z)| < \frac{\pi}{2}\Omega_i \quad \text{and} \quad \Re(\zeta_i) + 1 < 0, \quad (1.9)$$

where

$$\Omega_i = \sum_{j=1}^n \mathcal{B}_j + \sum_{j=1}^m \mathcal{G}_j - \tau_i \max_{1 \leq i \leq r} \left(\sum_{j=n+1}^{p_i} \mathcal{B}_{ji} + \sum_{j=m+1}^{q_i} \mathcal{G}_{ji} \right), \quad (1.10)$$

and

$$\zeta_i = \sum_{j=1}^m g_j - \sum_{j=1}^n a_j + \tau_i \left(\sum_{j=m+1}^{q_i} g_{ji} - \sum_{j=n+1}^{p_i} a_{ji} \right) + \frac{p_i - q_i}{2}, \quad i = 1, \dots, r. \quad (1.11)$$

Remark 1.1 It can easily be seen that

$$(\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z) + (\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z) = \aleph_{p_i, q_i, \tau_i; r}^{m, n}(z), \quad (1.12)$$

last of these functions is known as the Aleph-function (see, e.g., [5], [29]).

Letting $\xi \rightarrow 0$ in (1.1) (or $\xi \rightarrow \infty$ in (1.3)), the incomplete Aleph (\aleph)-functions reduce to the Aleph (\aleph)-functions.

If we set $\tau_i \rightarrow 1$, then the incomplete \aleph -functions $(\Gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ and $(\gamma)\aleph_{p_i, q_i, \tau_i; r}^{m, n}(z)$ reduce to incomplete I -functions $(\Gamma)I_{p_i, q_i; r}^{m, n}(z)$ and $(\gamma)I_{p_i, q_i; r}^{m, n}(z)$, respectively, given as follows:

$$\begin{aligned} (\Gamma)I_{p_i, q_i; r}^{m, n}(z) &:= (\Gamma)I_{p_i, q_i; r}^{m, n} \left[z \left| \begin{array}{l} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, n}, (a_{ji}, \mathcal{B}_{ji})_{n+1, p_i} \\ (g_j, \mathcal{G}_j)_{1, m}, (g_{ji}, \mathcal{G}_{ji})_{m+1, q_i} \end{array} \right. \right] \\ &= \frac{1}{2\pi\omega} \int_L \phi_3(s, \xi) z^{-s} ds, \end{aligned} \quad (1.13)$$

where

$$\phi_3(s, \xi) = \frac{\Gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\sum_{i=1}^r \left[\prod_{j=m+1}^{q_i} \Gamma(1 - g_{ji} - \mathcal{G}_{ji} s) \prod_{j=n+1}^{p_i} \Gamma(a_{ji} + \mathcal{B}_{ji} s) \right]}$$

and

$$(\gamma)I_{p_i, q_i; r}^{m, n}(z) := (\gamma)I_{p_i, q_i; r}^{m, n} \left[z \left| \begin{array}{l} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, n}, (a_{ji}, \mathcal{B}_{ji})_{n+1, p_i} \\ (g_j, \mathcal{G}_j)_{1, m}, (g_{ji}, \mathcal{G}_{ji})_{m+1, q_i} \end{array} \right. \right]$$

$$= \frac{1}{2\pi\omega} \int_L \phi_4(s, \xi) z^{-s} ds, \quad (1.14)$$

where

$$\phi_4(s, \xi) = \frac{\gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\sum_{i=1}^r \left[\prod_{j=m+1}^{q_i} \Gamma(1 - g_{ji} - \mathcal{G}_{ji} s) \prod_{j=n+1}^{p_i} \Gamma(a_{ji} + \mathcal{B}_{ji} s) \right]}.$$

The existence and other conditions can be obtained from the incomplete \aleph -functions in (1.1) and (1.3) when $\tau_i \rightarrow 1$.

Letting $r = 1$ in the incomplete I -functions $(\Gamma)I_{p_i, q_i; r}^{m, n}(z)$ and $(\gamma)I_{p_i, q_i; r}^{m, n}(z)$ reduce to incomplete H -functions $(\Gamma)H_{p, q}^{m, n}(z)$ and $(\gamma)H_{p, q}^{m, n}(z)$, respectively, given as follows:

$$\begin{aligned} (\Gamma)H_{p, q}^{m, n}(z) &= (\Gamma)H_{p, q}^{m, n} \left[z \left| \begin{array}{c} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, p} \\ (g_j, \mathcal{G}_j)_{1, q} \end{array} \right. \right] \\ &= \frac{1}{2\pi\omega} \int_L \phi_5(s, \xi) z^{-s} ds, \end{aligned} \quad (1.15)$$

where

$$\phi_5(s, \xi) = \frac{\Gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\prod_{j=m+1}^q \Gamma(1 - g_j - \mathcal{G}_j s) \prod_{j=n+1}^p \Gamma(a_j + \mathcal{B}_j s)}$$

and

$$\begin{aligned} (\gamma)H_{p, q}^{m, n}(z) &= (\gamma)H_{p, q}^{m, n} \left[z \left| \begin{array}{c} (a_1, \mathcal{B}_1, \xi), (a_j, \mathcal{B}_j)_{2, p} \\ (g_j, \mathcal{G}_j)_{1, q} \end{array} \right. \right] \\ &= \frac{1}{2\pi\omega} \int_L \phi_6(s, \xi) z^{-s} ds, \end{aligned} \quad (1.16)$$

where

$$\phi_6(s, \xi) = \frac{\gamma(1 - a_1 - \mathcal{B}_1 s, \xi) \prod_{j=2}^n \Gamma(1 - a_j - \mathcal{B}_j s) \prod_{j=1}^m \Gamma(g_j + \mathcal{G}_j s)}{\prod_{j=m+1}^q \Gamma(1 - g_j - \mathcal{G}_j s) \prod_{j=n+1}^p \Gamma(a_j + \mathcal{B}_j s)}.$$

The existence and other conditions can be obtained from the incomplete I -functions in (1.13) and (1.14) when $r = 1$.

Just as in the case of relation (1.12), the following relations hold:

$$(\Gamma)I_{p_i, q_i; r}^{m, n}(z) + (\gamma)I_{p_i, q_i; r}^{m, n}(z) = I_{p_i, q_i; r}^{m, n}(z), \quad (1.17)$$

last of these functions is known as the I -function (see, e.g., [30]);

$$(\Gamma)H_{p, q}^{m, n}(z) + (\gamma)H_{p, q}^{m, n}(z) = H_{p, q}^{m, n}(z), \quad (1.18)$$

last of these functions is known as the H -function (see, e.g., [31], [4]).

2. An Integral Involving Incomplete Aleph-Function

In this section, we present an important integral that involves the incomplete Aleph-function given in equation (1.1). This integral will play a key role in the next part of the paper, where we will use it as a foundation to prove Theorem 3.1.

Theorem 2.1 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral holds true*

$$\begin{aligned} \int_0^{\frac{\pi}{2}} \sin^{2\alpha-1} \theta \cos^{2\beta-1} \theta {}^{(\Gamma)}\aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[vz(\sin \theta)^{-2h} \left| \begin{array}{c} T_1 \\ T_2 \end{array} \right. \right] d\theta \\ = \frac{\Gamma(\beta)}{2} {}^{(\Gamma)}\aleph_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[vz \left| \begin{array}{c} T_1, (\alpha + \beta, h) \\ (\alpha, h), T_2 \end{array} \right. \right] \end{aligned} \quad (2.1)$$

where $T_1 = (a_1, \mathcal{B}_1, \xi)$, $(a_j, \mathcal{B}_j)_{2, n}$, $[\tau_i (a_{ji}, \mathcal{B}_{ji})]_{n+1, p_i}$

and $T_2 = (g_j, \mathcal{G}_j)_{1, m}$, $[\tau_i (g_{ji}, \mathcal{G}_{ji})]_{m+1, q_i}$

provided that $\Re \left\{ \alpha - h \left(\frac{a_j - 1}{\mathcal{B}_j} \right) \right\} > 0$, $j = 2 \dots n$ and other restrictions would be deducible from those in (1.1).

Proof: Let \mathcal{L}_1 be the left-handed member of (2.1). To establish (2.1), we need following formula

$$\int_0^{\frac{\pi}{2}} \sin^{2\alpha-1} \theta \cos^{2\beta-1} \theta d\theta = \frac{\Gamma(\alpha)\Gamma(\beta)}{2\Gamma(\alpha + \beta)}, \quad \Re(\alpha) > 0, \Re(\beta) > 0, \quad (2.2)$$

expressing incomplete Aleph-function in its contour integral from (1.1), interchanging the order of integration, which is permissible due to absolute convergence of the integrals involved in the process and evaluate inner integral by means of the integral (2.2), we have

$$\mathcal{L}_1 = \int_L \phi_1(s, \xi) (vz)^{-s} \left[\frac{\Gamma(\beta)\Gamma(\alpha + hs)}{2\Gamma(\alpha + \beta + hs)} \right] ds$$

which, upon expressing in terms of the incomplete Aleph-function (1.1), leads to the result in (2.1). This completes the proof. \square

3. Integral Relations of Incomplete Aleph-Functions

The object of the present paper is to study the following integral relations for incomplete Aleph-functions.

Theorem 3.1 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral relation holds true*

$$\begin{aligned} \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{1-\alpha-\beta} {}^{(\Gamma)}\aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \left| \begin{array}{c} T_1 \\ T_2 \end{array} \right. \right] f(x^2 + y^2) dy dx \\ = \frac{\Gamma(\beta)}{4} \int_0^\infty f(z) {}^{(\Gamma)}\aleph_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[vz \left| \begin{array}{c} T_1, (\alpha + \beta, h) \\ (\alpha, h), T_2 \end{array} \right. \right] dz \end{aligned} \quad (3.1)$$

where T_1 and T_2 are same as those in Theorem 2.1, provided that $\Re \left\{ \alpha - h \left(\frac{a_j - 1}{\mathcal{B}_j} \right) \right\} > 0$, $j = 2 \dots n$ and other restrictions would be deducible from those in (1.1).

Proof: Substituting $z = r^2$ in (2.1) and then multiplying both sides by $rf(r^2)$ and integrating between the limits $(0, \infty)$ with respect to r , we have

$$\begin{aligned} & \int_0^\infty rf(r^2)dr \int_0^{\frac{\pi}{2}} \sin^{2\alpha-1}\theta \cos^{2\beta-1}\theta {}^{(\Gamma)}\aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\begin{matrix} vr^2(\sin\theta)^{-2h} \\ T_2 \end{matrix} \middle| \begin{matrix} T_1 \\ T_2 \end{matrix} \right] d\theta \\ &= \frac{\Gamma(\beta)}{2} \int_0^\infty rf(r^2) {}^{(\Gamma)}\aleph_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[\begin{matrix} vr^2 \\ (\alpha, h), T_2 \end{matrix} \middle| T_1, (\alpha + \beta, h) \right] dr. \end{aligned}$$

Now on setting $x = r \cos \theta$, $y = r \sin \theta$ and making some simplifications, we get the required result (3.1). \square

Using the same method as in Theorem 3.1, we may reach the conclusion for the incomplete Aleph-function (1.3) as stated in the subsequent theorem.

Theorem 3.2 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral relation holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1}y^{2\alpha-1}(x^2+y^2)^{1-\alpha-\beta} {}^{(\gamma)}\aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\begin{matrix} v(x^2+y^2)^{h+1} \\ y^{2h} \end{matrix} \middle| \begin{matrix} T_1 \\ T_2 \end{matrix} \right] f(x^2+y^2)dydx \\ &= \frac{\Gamma(\beta)}{4} \int_0^\infty f(z) {}^{(\gamma)}\aleph_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[\begin{matrix} vz \\ (\alpha, h), T_2 \end{matrix} \middle| T_1, (\alpha + \beta, h) \right] dz \end{aligned} \quad (3.2)$$

where T_1 and T_2 are same as those in Theorem 2.1, provided that $\Re\left\{\alpha - h\left(\frac{a_j-1}{B_j}\right)\right\} > 0$, $j = 2 \dots n$ and other restrictions would be deducible from those in (1.1).

4. Applications Based on the Integral Relations of Incomplete Aleph-Functions

For practical use, double integrals can be solved more easily by choosing a suitable form for $f(z)$. This means that the integral on the right side of equation (3.1) is either already known or becomes easier to evaluate. Below, we give some examples to show how this can be applied.

Theorem 4.1 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1}y^{2\alpha-1}(x^2+y^2)^{-\alpha-\beta} \sin(x^2+y^2)^{\frac{1}{\sigma}} J_\nu(x^2+y^2)^{\frac{1}{\sigma}} \\ & \quad \times {}^{(\Gamma)}\aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\begin{matrix} v(x^2+y^2)^{h+1} \\ y^{2h} \end{matrix} \middle| \begin{matrix} T_1 \\ T_2 \end{matrix} \right] dydx \\ &= 2^{\nu-3} \sigma \Gamma(\beta) {}^{(\Gamma)}\aleph_{p_i+4, q_i+2, \tau_i; \kappa}^{m+2, n+1} \left[\begin{matrix} v \\ \omega_3, T_2 \end{matrix} \middle| \begin{matrix} \omega_1, T_1, \omega_2 \end{matrix} \right] \end{aligned} \quad (4.1)$$

where $\omega_1 = \left(\frac{1}{2} + \frac{\nu}{2} + \sigma, \frac{\sigma}{2}\right)$, $\omega_2 = (\alpha + \beta, h), (1 + \nu - 2\sigma, \sigma), \left(1 - \frac{\nu}{2} - \sigma, \frac{\sigma}{2}\right)$ and $\omega_3 = (\alpha, h), \left(\frac{1}{2} - 2\sigma, \sigma\right)$, T_1 and T_2 are same as those in Theorem 2.1, provided that

- (i) $\Re\left\{\nu + 2\sigma + \sigma\left(\frac{g_j}{G_{j_i}}\right)\right\} > -1$, $j = 1 \dots m$.
- (ii) $\Re\left\{\alpha - h\left(\frac{a_j-1}{B_j}\right)\right\} > 0$, $j = 2 \dots n$.
- (iii) $\Re\left\{4\sigma + 2\sigma\left(\frac{a_j-1}{B_j}\right)\right\} < 1$, $j = 2 \dots n$.

and other restrictions would be deducible from those in (1.1).

Proof: If we take $f(z) = z \sin\left(z^{\frac{1}{\sigma}}\right) J_\nu\left(z^{\frac{1}{\sigma}}\right)$, therefore, we have from relation (3.1).

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{-\alpha-\beta} \sin(x^2 + y^2)^{\frac{1}{\sigma}} J_\nu(x^2 + y^2)^{\frac{1}{\sigma}} \\ & \quad \times {}^{(\Gamma)}\mathfrak{N}_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{array}{c} T_1 \\ T_2 \end{array} \right] dy dx \\ & = \frac{\Gamma(\beta)}{4} \int_0^\infty z \sin\left(z^{\frac{1}{\sigma}}\right) J_\nu\left(z^{\frac{1}{\sigma}}\right) {}^{(\Gamma)}\mathfrak{N}_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[vz \middle| \begin{array}{c} T_1, (\alpha + \beta, h) \\ (\alpha, h), T_2 \end{array} \right] dz. \end{aligned} \quad (4.2)$$

Let \mathcal{L}_2 be the left-handed member of (4.2). Expressing incomplete Aleph-function in its contour integral from (1.1) in right-handed member of (4.2), interchanging the order of integration and setting $z = (ax)^\sigma$, we have

$$\begin{aligned} \mathcal{L}_2 & = \frac{\Gamma(\beta)}{4} \int_L \phi_1(s, \xi) v^{-s} \frac{\Gamma(\alpha + hs)}{\Gamma(\alpha + \beta + hs)} \\ & \quad \times \sigma a^{2\sigma - \sigma s} \left\{ \int_0^\infty x^{2\sigma - \sigma s - 1} \sin(ax) J_\nu(ax) dx \right\} ds. \end{aligned} \quad (4.3)$$

Recall the following Mellin transform (see, e.g., [32, p. 328, Entry (10)]):

$$\begin{aligned} \mathcal{M}\{\sin(ax) J_\nu(ax)\} & = \int_0^\infty x^{\rho-1} \sin(ax) J_\nu(ax) dx \\ & = \frac{2^{\nu-1} \Gamma(\frac{1}{2} - \rho) \Gamma(\frac{1}{2} + \frac{\nu}{2} + \frac{\rho}{2})}{a^\rho \Gamma(1 + \nu - \rho) \Gamma(1 - \frac{\nu}{2} - \frac{\rho}{2})}, \\ & \quad \left(a > 0, -1 < \Re(\nu) < \Re(\rho) < \frac{1}{2} \right), \end{aligned} \quad (4.4)$$

using (4.4) to evaluate the inner integral in (4.3), then, upon expressing in terms of the incomplete Aleph-function (1.1), leads to the result in (4.1). This completes the proof. \square

Theorem 4.2 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{1}{2h}(1-u) - \alpha - \beta} J_\mu(x^2 + y^2)^{\frac{1}{2h}} J_\nu(x^2 + y^2)^{\frac{1}{2h}} \\ & \quad \times {}^{(\Gamma)}\mathfrak{N}_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{array}{c} T_1 \\ T_2 \end{array} \right] dy dx \\ & = \frac{h \Gamma(\beta)}{2^{u+1}} {}^{(\Gamma)}\mathfrak{N}_{p_i+5, q_i+2, \tau_i; \kappa}^{m+2, n+1} \left[2^h v \middle| \begin{array}{c} \omega_4, T_1, \omega_5 \\ \omega_6, T_2 \end{array} \right] \end{aligned} \quad (4.5)$$

where $\omega_4 = \left(\frac{1+u-\nu-\mu}{2}, h\right)$, $\omega_5 = (\alpha + \beta, h)$, $\left(\frac{1+u+\mu+\nu}{2}, h\right)$, $\left(\frac{1+u-\mu+\nu}{2}, h\right)$, $\left(\frac{1+u+\mu-\nu}{2}, h\right)$ and $\omega_6 = (\alpha, h)$, $(u, 2h)$, T_1 and T_2 are same as those in Theorem 2.1, provided that

- (i) $\Re\left\{\mu + \nu - u + 2h \left(\frac{g_j}{g_{ji}}\right)\right\} > -1$, $j = 1 \dots m$.
- (ii) $\Re\left\{u - 2h \left(\frac{a_j - 1}{B_j}\right)\right\} > 0$, $j = 2 \dots n$.

$$(iii) \Re \left\{ \alpha - h \left(\frac{a_j - 1}{B_j} \right) \right\} > 0, j = 2 \dots n.$$

and other restrictions would be deducible from those in (1.1).

Proof: On taking $f(z) = z^{\frac{1}{2h}(1-u)-1} J_\mu(z^{\frac{1}{2h}}) J_\nu(z^{\frac{1}{2h}})$ and using the following formula (see, e.g., [33, p. 342, Entry (24)]):

$$\int_0^\infty x^{-\rho} J_\mu(ax) J_\nu(ax) dx = \frac{2^{-\rho} \Gamma(\rho) \Gamma\left(\frac{\mu+\nu-\rho+1}{2}\right)}{\Gamma\left(\frac{\mu+\nu+\rho+1}{2}\right) \Gamma\left(\frac{\rho-\mu+\nu+1}{2}\right) \Gamma\left(\frac{\mu-\nu+\rho+1}{2}\right)}, \quad (4.6)$$

$$(0 < \Re(\rho) < \Re(\mu + \nu) + 1),$$

result in (4.5) can easily be established. \square

Theorem 4.3 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{\lambda+1}{\sigma} - \alpha - \beta} {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -\delta(x^2 + y^2)^{\frac{1}{\sigma}} \right] \\ & \times {}^{(\Gamma)} \mathfrak{N}_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\begin{matrix} v(x^2 + y^2)^{h+1} \\ y^{2h} \end{matrix} \middle| \begin{matrix} T_1 \\ T_2 \end{matrix} \right] dy dx \\ & = \frac{\sigma \Gamma(\beta) \Gamma(c)}{4 \Gamma(a) \Gamma(b) \delta^{\lambda+1}} {}^{(\Gamma)} \mathfrak{N}_{p_i+3, q_i+3, \tau_i; \kappa}^{m+3, n+1} \left[\begin{matrix} v \\ \delta^\sigma \end{matrix} \middle| \begin{matrix} (-\lambda, \sigma), T_1, (\alpha + \beta, h), (c - \lambda - 1, \sigma) \\ (a - \lambda - 1, \sigma), (b - \lambda - 1, \sigma), (\alpha, h), T_2 \end{matrix} \right] \end{aligned} \quad (4.7)$$

where T_1 and T_2 are same as those in Theorem 2.1, provided that

$$(i) \Re \left\{ \lambda + \sigma \left(\frac{g_j}{g_{ji}} \right) \right\} > -1, j = 1 \dots m.$$

$$(ii) \Re \left\{ \lambda + 1 + \sigma \left(\frac{a_j - 1}{B_j} \right) \right\} < a, j = 2 \dots n.$$

$$(iii) \Re \left\{ \lambda + 1 + \sigma \left(\frac{a_j - 1}{B_j} \right) \right\} < b, j = 2 \dots n.$$

and other restrictions would be deducible from those in (1.1).

Proof: On taking $f(z) = z^{\frac{\lambda+1}{\sigma}-1} {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -\delta z^{\frac{1}{\sigma}} \right]$ and using the following Mellin transform formula of Gauss hypergeometric function with a negative argument (see, e.g., [32, p. 336, Entry (3)], for new research related to transforms, see [34], [35]):

$$\begin{aligned} \mathcal{M} \left\{ {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -x \right] \right\} &= \int_0^\infty x^{\rho-1} {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -x \right] dx \\ &= \frac{B(\rho, a - \rho) B(\rho, b - \rho)}{B(\rho, c - \rho)}, \\ &(0 < \Re(\rho) < \min(\Re(a), \Re(b)), \end{aligned} \quad (4.8)$$

result in (4.7) can easily be established. \square

Remark 4.1

By following the same method used in Theorems 4.1, 4.2, and 4.3, we can also derive similar types of results for the incomplete Aleph-function given in equation (1.3).

5. Particular Cases

The incomplete Aleph-function is considered a broad and unified function since many well-known special functions can be obtained from it by adjusting its parameters. Because of this, it is highly flexible and useful. In this section, we demonstrate that by selecting suitable parameter values, how the results of this study lead to several significant outcomes as particular cases.

Letting $\tau_i \rightarrow 1$, in Theorem 3.1, we find an integral relation for incomplete I -function in (1.13) as in the following corollary.

Corollary 5.1 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral relation holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{1-\alpha-\beta} {}^{(\Gamma)} I_{p_i, q_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \left| \begin{array}{c} T_3 \\ T_4 \end{array} \right. \right] f(x^2 + y^2) dy dx \\ &= \frac{\Gamma(\beta)}{4} \int_0^\infty f(z) {}^{(\Gamma)} I_{p_i+1, q_i+1; \kappa}^{m+1, n} \left[vz \left| \begin{array}{c} T_3, (\alpha + \beta, h) \\ (\alpha, h), T_4 \end{array} \right. \right] dz \end{aligned} \quad (5.1)$$

where $T_3 = (a_1, \mathcal{B}_1, \xi)$, $(a_j, \mathcal{B}_j)_{2, n}$, $(a_{ji}, \mathcal{B}_{ji})_{n+1, p_i}$

and $T_4 = (g_j, \mathcal{G}_j)_{1, m}$, $(g_{ji}, \mathcal{G}_{ji})_{m+1, q_i}$,

provided that $\Re \left\{ \alpha - h \left(\frac{a_j - 1}{\mathcal{B}_j} \right) \right\} > 0$, $j = 2 \dots n$ and other restrictions would be deducible from those in (1.1).

Letting $\tau_i \rightarrow 1$ and $\kappa \rightarrow 1$ in Theorem 3.1, we find an integral relation for incomplete H -function in (1.15) as in the following corollary.

Corollary 5.2 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral relation holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{1-\alpha-\beta} {}^{(\Gamma)} H_{p, q}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \left| \begin{array}{c} T_5 \\ T_6 \end{array} \right. \right] f(x^2 + y^2) dy dx \\ &= \frac{\Gamma(\beta)}{4} \int_0^\infty f(z) {}^{(\Gamma)} H_{p+1, q+1}^{m+1, n} \left[vz \left| \begin{array}{c} T_5, (\alpha + \beta, h) \\ (\alpha, h), T_6 \end{array} \right. \right] dz \end{aligned} \quad (5.2)$$

where $T_5 = (a_1, \mathcal{B}_1, \xi)$, $(a_j, \mathcal{B}_j)_{2, p}$

and $T_6 = (g_j, \mathcal{G}_j)_{1, q}$

provided that $\Re \left\{ \alpha - h \left(\frac{a_j - 1}{\mathcal{B}_j} \right) \right\} > 0$, $j = 2 \dots n$ and other restrictions would be deducible from those in (1.1).

Letting $\tau_i \rightarrow 1$, in Theorems 4.1, 4.2, and 4.3, the results turn out to be that for the incomplete I -function in (1.13) as in the following corollaries.

Corollary 5.3 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{-\alpha-\beta} \sin(x^2 + y^2)^{\frac{1}{\sigma}} J_\nu(x^2 + y^2)^{\frac{1}{\sigma}} \\ & \times {}^{(\Gamma)} I_{p_i, q_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \left| \begin{array}{c} T_3 \\ T_4 \end{array} \right. \right] dy dx \\ &= 2^{\nu-3} \sigma \Gamma(\beta) {}^{(\Gamma)} I_{p_i+4, q_i+2, ; \kappa}^{m+2, n+1} \left[v \left| \begin{array}{c} \omega_1, T_3, \omega_2 \\ \omega_3, T_4 \end{array} \right. \right] \end{aligned} \quad (5.3)$$

where $\omega_1 = (\frac{1}{2} + \frac{\nu}{2} + \sigma, \frac{\sigma}{2})$, $\omega_2 = (\alpha + \beta, h), (1 + \nu - 2\sigma, \sigma), (1 - \frac{\nu}{2} - \sigma, \frac{\sigma}{2})$
and $\omega_3 = (\alpha, h), (\frac{1}{2} - 2\sigma, \sigma)$, T_3 and T_4 are same as those in Corollary 5.1. The convergence conditions would follow from those in Theorem 4.1 and other restrictions would be deducible from those in (1.1).

Corollary 5.4 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{1}{2h}(1-u)-\alpha-\beta} J_\mu(x^2 + y^2)^{\frac{1}{2h}} J_\nu(x^2 + y^2)^{\frac{1}{2h}} \\ & \quad \times {}^{(\Gamma)}I_{p_i, q_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_3 \\ T_4 \end{matrix} \right] dy dx \\ & = \frac{h \Gamma(\beta)}{2^{u+1}} {}^{(\Gamma)}I_{p_i+5, q_i+2; \kappa}^{m+2, n+1} \left[2^h v \middle| \begin{matrix} \omega_4, T_3, \omega_5 \\ \omega_6, T_4 \end{matrix} \right] \end{aligned} \quad (5.4)$$

where $\omega_4 = (\frac{1+u-\nu-\mu}{2}, h)$, $\omega_5 = (\alpha + \beta, h), (\frac{1+u+\mu+\nu}{2}, h), (\frac{1+u-\mu+\nu}{2}, h), (\frac{1+u+\mu-\nu}{2}, h)$
and $\omega_6 = (\alpha, h), (u, 2h)$, T_3 and T_4 are same as those in Corollary 5.1. The convergence conditions would follow from those in Theorem 4.2 and other restrictions would be deducible from those in (1.1).

Corollary 5.5 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{\lambda+1}{\sigma}-\alpha-\beta} {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -\delta(x^2 + y^2)^{\frac{1}{\sigma}} \right] \\ & \quad \times {}^{(\Gamma)}I_{p_i, q_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_3 \\ T_4 \end{matrix} \right] dy dx \\ & = \frac{\sigma \Gamma(\beta) \Gamma(c)}{4 \Gamma(a) \Gamma(b) \delta^{\lambda+1}} {}^{(\Gamma)}I_{p_i+3, q_i+3; \kappa}^{m+3, n+1} \left[\frac{v}{\delta^\sigma} \middle| \begin{matrix} (-\lambda, \sigma), T_3, (\alpha + \beta, h), (c - \lambda - 1, \sigma) \\ (a - \lambda - 1, \sigma), (b - \lambda - 1, \sigma), (\alpha, h), T_4 \end{matrix} \right] \end{aligned} \quad (5.5)$$

where T_3 and T_4 are same as those in Corollary 5.1. The convergence conditions would follow from those in Theorem 4.3 and other restrictions would be deducible from those in (1.1).

Letting $\tau_i \rightarrow 1$, and $\kappa \rightarrow 1$ in Theorems 4.1, 4.2, and 4.3, the results turn out to be that for the incomplete H -function in (1.15) as in the following corollaries.

Corollary 5.6 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{-\alpha-\beta} \sin(x^2 + y^2)^{\frac{1}{\sigma}} J_\nu(x^2 + y^2)^{\frac{1}{\sigma}} \\ & \quad \times {}^{(\Gamma)}H_{p, q}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_5 \\ T_6 \end{matrix} \right] dy dx \\ & = 2^{\nu-3} \sigma \Gamma(\beta) {}^{(\Gamma)}H_{p+4, q+2}^{m+2, n+1} \left[v \middle| \begin{matrix} \omega_1, T_5, \omega_2 \\ \omega_3, T_6 \end{matrix} \right] \end{aligned} \quad (5.6)$$

where $\omega_1 = (\frac{1}{2} + \frac{\nu}{2} + \sigma, \frac{\sigma}{2})$, $\omega_2 = (\alpha + \beta, h), (1 + \nu - 2\sigma, \sigma), (1 - \frac{\nu}{2} - \sigma, \frac{\sigma}{2})$
and $\omega_3 = (\alpha, h), (\frac{1}{2} - 2\sigma, \sigma)$, T_5 and T_6 are same as those in Corollary 5.2. The convergence conditions would follow from those in Theorem 4.1 and other restrictions would be deducible from those in (1.1).

Corollary 5.7 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{1}{2h}(1-u)-\alpha-\beta} J_\mu(x^2 + y^2)^{\frac{1}{2h}} J_\nu(x^2 + y^2)^{\frac{1}{2h}} \\ & \quad \times {}^{(\Gamma)}H_{p,q}^{m,n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_5 \\ T_6 \end{matrix} \right] dy dx \\ & = \frac{h \Gamma(\beta)}{2^{u+1}} {}^{(\Gamma)}H_{p+5,q+2}^{m+2,n+1} \left[2^{h\nu} \middle| \begin{matrix} \omega_4, T_5, \omega_5 \\ \omega_6, T_6 \end{matrix} \right] \end{aligned} \quad (5.7)$$

where $\omega_4 = (\frac{1+u-\nu-\mu}{2}, h)$, $\omega_5 = (\alpha + \beta, h)$, $(\frac{1+u+\mu+\nu}{2}, h)$, $(\frac{1+u-\mu+\nu}{2}, h)$, $(\frac{1+u+\mu-\nu}{2}, h)$ and $\omega_6 = (\alpha, h), (u, 2h)$, T_5 and T_6 are same as those in Corollary 5.2. The convergence conditions would follow from those in Theorem 4.2 and other restrictions would be deducible from those in (1.1).

Corollary 5.8 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{\lambda+1}{\sigma}-\alpha-\beta} {}_2F_1 \left[\begin{matrix} a, b \\ c \end{matrix} \middle| -\delta(x^2 + y^2)^{\frac{1}{\sigma}} \right] \\ & \quad \times {}^{(\Gamma)}H_{p,q}^{m,n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_5 \\ T_6 \end{matrix} \right] dy dx \\ & = \frac{\sigma \Gamma(\beta) \Gamma(c)}{4 \Gamma(a) \Gamma(b) \delta^{\lambda+1}} {}^{(\Gamma)}H_{p+3,q+3}^{m+3,n+1} \left[\frac{v}{\delta^\sigma} \middle| \begin{matrix} (-\lambda, \sigma), T_5, (\alpha + \beta, h), (c - \lambda - 1, \sigma) \\ (a - \lambda - 1, \sigma), (b - \lambda - 1, \sigma), (\alpha, h), T_6 \end{matrix} \right] \end{aligned} \quad (5.8)$$

where T_5 and T_6 are same as those in Corollary 5.2. The convergence conditions would follow from those in Theorem 4.3 and other restrictions would be deducible from those in (1.1).

Letting $\xi \rightarrow 0$, in Theorem 3.1, we find an integral relation for Aleph (\aleph)-function (see, e.g., [5], [29]) as in the following corollary.

Corollary 5.9 Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following integral relation holds true

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{1-\alpha-\beta} \aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{matrix} T_7 \\ T_8 \end{matrix} \right] f(x^2 + y^2) dy dx \\ & = \frac{\Gamma(\beta)}{4} \int_0^\infty f(z) \aleph_{p_i+1, q_i+1, \tau_i; \kappa}^{m+1, n} \left[vz \middle| \begin{matrix} T_7, (\alpha + \beta, h) \\ (\alpha, h), T_8 \end{matrix} \right] dz \end{aligned} \quad (5.9)$$

where $T_7 = (a_j, \mathcal{B}_j)_{1, n}, [\tau_i(a_{ji}, \mathcal{B}_{ji})]_{n+1, p_i}$

and $T_8 = (g_j, \mathcal{G}_j)_{1, m}, [\tau_i(g_{ji}, \mathcal{G}_{ji})]_{m+1, q_i}$

provided that $\Re \left\{ \alpha - h \left(\frac{a_j - 1}{\mathcal{B}_j} \right) \right\} > 0$, $j = 1 \dots n$ and other restrictions would be deducible from those in (1.1).

Letting $\xi \rightarrow 0$, in Theorems 4.1, 4.2, and 4.3, the results turn out to be that for Aleph (\aleph)-function (see, e.g., [5], [29]) as in the following corollaries.

Corollary 5.10 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{-\alpha-\beta} \sin(x^2 + y^2)^{\frac{1}{\sigma}} J_\nu(x^2 + y^2)^{\frac{1}{\sigma}} \\ & \quad \times \aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{array}{c} T_7 \\ T_8 \end{array} \right] dy dx \\ & = 2^{\nu-3} \sigma \Gamma(\beta) \aleph_{p_i+4, q_i+2, \tau_i; \kappa}^{m+2, n+1} \left[v \middle| \begin{array}{c} \omega_1, T_7, \omega_2 \\ \omega_3, T_8 \end{array} \right] \end{aligned} \quad (5.10)$$

where $\omega_1 = (\frac{1}{2} + \frac{\nu}{2} + \sigma, \frac{\sigma}{2})$, $\omega_2 = (\alpha + \beta, h), (1 + \nu - 2\sigma, \sigma), (1 - \frac{\nu}{2} - \sigma, \frac{\sigma}{2})$
and $\omega_3 = (\alpha, h), (\frac{1}{2} - 2\sigma, \sigma)$, T_7 and T_8 are same as those in Corollary 5.9, provided that

$$(i) \Re \left\{ \nu + 2\sigma + \sigma \left(\frac{g_j}{g_{ji}} \right) \right\} > -1, j = 1 \dots m.$$

$$(ii) \Re \left\{ \alpha - h \left(\frac{a_j - 1}{B_j} \right) \right\} > 0, j = 1 \dots n.$$

$$(iii) \Re \left\{ 4\sigma + 2\sigma \left(\frac{a_j - 1}{B_j} \right) \right\} < 1, j = 1 \dots n.$$

and other restrictions would be deducible from those in (1.1).

Corollary 5.11 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{1}{2h}(1-u)-\alpha-\beta} J_\mu(x^2 + y^2)^{\frac{1}{2h}} J_\nu(x^2 + y^2)^{\frac{1}{2h}} \\ & \quad \times \aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{array}{c} T_7 \\ T_8 \end{array} \right] dy dx \\ & = \frac{h \Gamma(\beta)}{2^{u+1}} \aleph_{p_i+5, q_i+2, \tau_i; \kappa}^{m+2, n+1} \left[2^h v \middle| \begin{array}{c} \omega_4, T_7, \omega_5 \\ \omega_6, T_8 \end{array} \right] \end{aligned} \quad (5.11)$$

where $\omega_4 = (\frac{1+u-\nu-\mu}{2}, h)$, $\omega_5 = (\alpha + \beta, h), (\frac{1+u+\mu+\nu}{2}, h), (\frac{1+u-\mu+\nu}{2}, h), (\frac{1+u+\mu-\nu}{2}, h)$
and $\omega_6 = (\alpha, h), (u, 2h)$, T_7 and T_8 are same as those in Corollary 5.9, provided that

$$(i) \Re \left\{ \mu + \nu - u + 2h \left(\frac{g_j}{g_{ji}} \right) \right\} > -1, j = 1 \dots m.$$

$$(ii) \Re \left\{ u - 2h \left(\frac{a_j - 1}{B_j} \right) \right\} > 0, j = 1 \dots n.$$

$$(iii) \Re \left\{ \alpha - h \left(\frac{a_j - 1}{B_j} \right) \right\} > 0, j = 1 \dots n.$$

and other restrictions would be deducible from those in (1.1).

Corollary 5.12 *Let $\Re(\alpha) > 0$, $\Re(\beta) > 0$ and h be a positive integer, then the following result holds true*

$$\begin{aligned} & \int_0^\infty \int_0^\infty x^{2\beta-1} y^{2\alpha-1} (x^2 + y^2)^{\frac{\lambda+1}{\sigma}-\alpha-\beta} {}_2F_1 \left[\begin{array}{c} a, b \\ c \end{array} \middle| -\delta(x^2 + y^2)^{\frac{1}{\sigma}} \right] \\ & \quad \times \aleph_{p_i, q_i, \tau_i; \kappa}^{m, n} \left[\frac{v(x^2 + y^2)^{h+1}}{y^{2h}} \middle| \begin{array}{c} T_7 \\ T_8 \end{array} \right] dy dx \\ & = \frac{\sigma \Gamma(\beta) \Gamma(c)}{4 \Gamma(a) \Gamma(b) \delta^{\lambda+1}} \aleph_{p_i+3, q_i+3, \tau_i; \kappa}^{m+3, n+1} \left[\frac{v}{\delta^\sigma} \middle| \begin{array}{c} (-\lambda, \sigma), T_7, (\alpha + \beta, h), (c - \lambda - 1, \sigma) \\ (a - \lambda - 1, \sigma), (b - \lambda - 1, \sigma), (\alpha, h), T_8 \end{array} \right] \end{aligned} \quad (5.12)$$

where T_7 and T_8 are same as those in Corollary 5.9, provided that

$$(i) \Re \left\{ \lambda + \sigma \left(\frac{g_j}{g_{ji}} \right) \right\} > -1, j = 1 \dots m.$$

$$(ii) \Re \left\{ \lambda + 1 + \sigma \left(\frac{a_j - 1}{B_j} \right) \right\} < a, j = 1 \dots n.$$

$$(iii) \Re \left\{ \lambda + 1 + \sigma \left(\frac{a_j - 1}{B_j} \right) \right\} < b, j = 1 \dots n.$$

and other restrictions would be deducible from those in (1.1).

Remark 5.1

By appropriately specializing the parameters in Theorems 3.1, 4.1, 4.2, and 4.3, analogous results can also be obtained for Saxena's I -function and Fox's H -function.

6. Conclusion

In this work, we explored new integral relations for incomplete Aleph-functions and showed how these relations can be used to solve certain double integrals more easily. By applying known mathematical results, we simplified integrals involving Bessel functions, hypergeometric functions, and incomplete Aleph-functions. The formulas we developed are broad and flexible, and the special examples we provided demonstrate how these results can be applied in practical situations. Overall, this work contributes to the ongoing development of Aleph-function theory and offers practical tools for future analytical investigations.

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